Università della Svizzera italiana	Institute of Computing CI

### High-Performance Computing Lab

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Discussed with: —

# Solution for Project 1

Due date: 12.10.2022 (midnight)



In this project you will practice memory access optimization, performance-oriented programming, and OpenMP parallelizaton on the ICS Cluster .

## 1. Explaining Memory Hierarchies

# (25 Points)

#### 1.1. Memory Hierarchy Parameters of the Cluster

By identifying the memory hierarchy parameters through likwid-topology for the cache topology and free -g for the amount of primary memory I find the following values:

Main memory	62  GB
L3 cache	25  MB per socket
L2 cache	256  kB per core
L1 cache	32  kB per core

All values are reported using base 2 IEC byte units. The cluster has 2 sockets and a total of 20 cores (10 per socket). The cache topology diagram reported by likwid-topology -g is the following:

+	+ ++	+	+ ++	++	++	++	++	++	++
0		2	3	4	5	6	7	8	9
+	+ ++	+	+ ++	++	++	++	++	++	++
32 kB	32 kB	32 kB	32 kB	32 kB	32 kB	32 kB	32 kB	32 kB	32 kB
+	+ ++	+	+ ++	++	++	++	++	++	++
+	+ ++	+	+ ++	++	++	++	++	++	++
+	+ ++	+	+ ++	++	++	++	++	++	++
+									+
I				25	MB				I
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cket 1:	+ ++		 	 		++		++	 ++
cket 1: +	 + ++     11	+	+ ++     13	++   14	++   15	++	++   17	++	++
cket 1:  +   10 +	+ ++     11   + ++	+	+ ++     13   + ++	++   14   ++	++   15   ++	++   16   ++	++   17   ++	++   18   ++	++   19   ++
cket 1: +   10 +	+ ++     11   + ++ + ++	+   12 +	+ ++     13   + ++ + ++	++   14   ++ ++	++   15   ++ ++	++   16   ++ ++	++   17   ++ ++	++   18   ++ ++	++   19   ++ ++
cket 1: +   10 +   32 kB	+ ++     11   + ++ + ++     32 kB   + ++	+   12 +   32 kB +	+ ++     13   + ++     32 kB   + ++	++   14   ++   32 kB   ++	++   15   ++   32 kB   ++	++   16   ++   32 kB	++   17   ++   32 kB   ++	++   18   ++ ++   32 kB   ++	19   + +   32 kB
cket 1: +   10 +   32 kB +	+ ++     11   + ++ + ++     32 kB   + +++	+   12 +   32 kB +	+ ++ ++ + ++ ++ + ++ + +++	++   14   ++   32 kB   ++	++   15   ++   32 kB   ++	++   16   ++   32 kB   +++	++   17   ++   32 kB   ++	++   18   ++   32 kB   ++	++   19 ++   32 kB   ++
	+ ++ + ++ + ++   32 kB   + ++ + ++   256 kB	12 +	+ ++ + ++ + ++   32 kB   + +++ + ++   256 kB	++   14   ++   32 kB   ++ +   256 kB	++   15   ++   32 kB   ++   256 kB	++   16   ++   32 kB   ++ +   256 kB	17   ++   32 kB   ++   256 kB	++   18   ++   32 kB   ++ +   256 kB	++   19   ++   32 kB   ++ ++   256 kB
	+ ++ + ++ ++ ++ + ++ + +++   256 kB   + +++	12 +   32 kB +   256 kB	+ ++ + +++ + ++++ + ++++ + ++++ + ++++ + ++++ + ++++ + ++++ + +++++ + +++++ + +++++ + ++++++ + +++++++ + +++++++++++	14   ++   32 kB   ++   256 kB   ++	++   15   ++   32 kB   ++   256 kB   ++	16   +	17   ++   32 kB   ++   256 kB   ++	18   ++   32 kB   ++   256 kB   ++	19   +
	+ ++     11   + ++     32 kB   + ++ + +++ + +++	+   12 +   32 kB +   256 kB	+ ++     13   ++     32 kB   ++ ++     256 kB   ++	14   ++   32 kB   ++   256 kB   ++	++   15   ++   32 kB   ++   256 kB   ++	16   +	++   17   ++   32 kB   ++   256 kB   ++	18   ++   32 kB   ++   256 kB   ++	19 +

#### 1.2. Memory Access Pattern of membench.c

The benchmark membench.c measures the average time of repeated read and write overations across a set of indices of a stack-allocated array of 32-bit signed integers. The indices vary according to the access pattern used, which in turn is defined by two variables, csize and stride. csize is an upper bound on the index value, i.e. (one more of) the highest index used to access the array in the pattern. stride determines the difference between array indexes over access iterations, i.e. a stride of 1 will access every array index, a stride of 2 will skip every other index, a stride of 4 will access one index then skip 3 and so on and so forth.

Therefore, for csize = 128 and stride = 1 the array will access all indexes between 0 and 127 sequentially, and for csize =  $2^{20}$  and stride =  $2^{10}$  the benchmark will access index 0, then index  $2^{10} - 1$ , and finally index  $2^{20} - 1$ i.

#### 1.3. Analyzing Benchmark Results

The membench.c benchmark results for my personal laptop (Macbook Pro 2018 with a Core i7-8750H CPU) and the cluster are shown below respectively:





The memory access graph for the cluster's benchmark results shows that temporal locality is best for small array sizes and for small **stride** values. In particular, for array memory sizes of 16MB or lower (csize of  $4 \cdot 2^{20}$  or lower) and **stride** values of 2048 or lower the mean read+write time is less than 10 nanoseconds. Temporal locality is worst for large sizes and strides, although the largest values of **stride** for each size (like csize / 2 and csize / 4) achieve better mean times due to the few elements accessed in the pattern (this observation is also valid for the largest strides of each size series shown in the graph).

## 2. Optimize Square Matrix-Matrix Multiplication (60 Points)

### 3. Quality of the Report

(15 Points)