

# Assignment 2

June 8, 2021

## 1 Assignment 2

### 1.0.1 Claudio Maggioni

```
[2]: import os
import pickle
import urllib.request as http
from zipfile import ZipFile

import tensorflow as tf
import numpy as np
from PIL import Image

from tensorflow.keras import layers as keras_layers
from tensorflow.keras import backend as K
from tensorflow.keras.datasets import cifar10
from tensorflow.keras.models import save_model, load_model

def load_cifar10(num_classes=3):
    """
    Downloads CIFAR-10 dataset, which already contains a training and test set,
    and return the first `num_classes` classes.
    Example of usage:

    >>> (x_train, y_train), (x_test, y_test) = load_cifar10()

    :param num_classes: int, default is 3 as required by the assignment.
    :return: the filtered data.
    """
    (x_train_all, y_train_all), (x_test_all, y_test_all) = cifar10.load_data()

    fil_train = tf.where(y_train_all[:, 0] < num_classes)[:, 0]
    fil_test = tf.where(y_test_all[:, 0] < num_classes)[:, 0]

    y_train = y_train_all[fil_train]
    y_test = y_test_all[fil_test]
```

```

x_train = x_train_all[fil_train]
x_test = x_test_all[fil_test]

return (x_train, y_train), (x_test, y_test)

def load_rps(download=False, path='rps', reduction_factor=1):
    """
    Downloads the rps dataset and returns the training and test sets.
    Example of usage:

    >>> (x_train, y_train), (x_test, y_test) = load_rps()

    :param download: bool, default is False but for the first call should be
    ↪ True.
    :param path: str, subdirectory in which the images should be downloaded,
    ↪ default is 'rps'.
    :param reduction_factor: int, factor of reduction of the dataset (len =
    ↪ old_len // reduction_factor).
    :return: the images and labels split into training and validation sets.
    """
    url = 'https://drive.switch.ch/index.php/s/xjXhuYDUzoZvL02/download'
    classes = ('rock', 'paper', 'scissors')
    rps_dir = os.path.abspath(path)
    filename = os.path.join(rps_dir, 'data.zip')
    if not os.path.exists(rps_dir) and not download:
        raise ValueError("Dataset not in the path. You should call this
    ↪ function with `download=True` the first time.")
    if download:
        os.makedirs(rps_dir, exist_ok=True)
        print(f"Downloading rps images in {rps_dir} (may take a couple of
    ↪ minutes)")
        path, msg = http.urlretrieve(url, filename)
        with ZipFile(path, 'r') as zip_ref:
            zip_ref.extractall(rps_dir)
        os.remove(filename)
    train_dir, test_dir = os.path.join(rps_dir, 'train'), os.path.join(rps_dir,
    ↪ 'test')
    print("Loading training set...")
    x_train, y_train = load_images_with_label(train_dir, classes)
    x_train, y_train = x_train[::reduction_factor], y_train[::reduction_factor]
    print("Loaded %d images for training" % len(y_train))
    print("Loading test set...")
    x_test, y_test = load_images_with_label(test_dir, classes)
    x_test, y_test = x_test[::reduction_factor], y_test[::reduction_factor]
    print("Loaded %d images for testing" % len(y_test))

```

```

    return (x_train, y_train), (x_test, y_test)

def make_dataset(imgs, labels, label_map, img_size, rgb=True, keepdim=True,
↳shuffle=True):
    x = []
    y = []
    n_classes = len(list(label_map.keys()))
    for im, l in zip(imgs, labels):
        # preprocess img
        x_i = im.resize(img_size)
        if not rgb:
            x_i = x_i.convert('L')
        x_i = np.asarray(x_i)
        if not keepdim:
            x_i = x_i.reshape(-1)

        # encode label
        y_i = np.zeros(n_classes)
        y_i[label_map[l]] = 1.

        x.append(x_i)
        y.append(y_i)
    x, y = np.array(x).astype('float32'), np.array(y)
    if shuffle:
        idxs = np.arange(len(y))
        np.random.shuffle(idxs)
        x, y = x[idxs], y[idxs]
    return x, y

def load_images(path):
    img_files = os.listdir(path)
    imgs, labels = [], []
    for i in img_files:
        if i.endswith('.jpg'):
            # load the image (here you might want to resize the img to save
↳memory)
            imgs.append(Image.open(os.path.join(path, i)).copy())
    return imgs

def load_images_with_label(path, classes):
    imgs, labels = [], []
    for c in classes:
        # iterate over all the files in the folder
        c_imgs = load_images(os.path.join(path, c))

```

```

        imgs.extend(c_imgs)
        labels.extend([c] * len(c_imgs))
    return imgs, labels

def save_keras_model(model, filename):
    """
    Saves a Keras model to disk.
    Example of usage:

    >>> model = Sequential()
    >>> model.add(Dense(...))
    >>> model.compile(...)
    >>> model.fit(...)
    >>> save_keras_model(model, 'my_model.h5')

    :param model: the model to save;
    :param filename: string, path to the file in which to store the model.
    :return: the model.
    """
    save_model(model, filename)

def load_keras_model(filename):
    """
    Loads a compiled Keras model saved with models.save_model.

    :param filename: string, path to the file storing the model.
    :return: the model.
    """
    model = load_model(filename)
    return model

def save_vgg16(model, filename='nn_task2.pkl', additional_args=()):
    """
    Optimize task2 model by only saving the layers after vgg16. This function
    assumes that you only added Flatten and Dense layers. If it is not the case,
    you should include into `additional_args` other layers' attributes you
    need.

    :param filename: string, path to the file in which to store the model.
    :param additional_args: tuple or list, additional layers' attributes to be
    saved. Default are ['units', 'activation', 'use_bias']
    :return: the path of the saved model.
    """
    filename = filename if filename.endswith('.pkl') else (filename + '.pkl')

```

```

args = ['units', 'activation', 'use_bias', *additional_args]
layers = []
for l in model.layers[1:]:
    layer = dict()
    layer['class'] = l.__class__.__name__
    if l.weights:
        layer['weights'] = l.get_weights()
        layer['kwargs'] = {k: v for k, v in vars(l).items() if k in args}
    layers.append(layer)

with open(filename, 'wb') as fp:
    pickle.dump(layers, fp)

return os.path.abspath(filename)

def load_vgg16(filename='nn_task2.pkl', img_h=224, img_w=224):
    """
    Loads the model saved with save_vgg16.

    :param filename: string, path to the file storing the model.
    :param img_h: int, the height of the input image.
    :param img_w: int, the width of the input image.
    :return: the model.
    """
    K.clear_session()

    vgg16 = applications.VGG16(weights='imagenet',
                               include_top=False,
                               input_shape=(img_h, img_w, 3))

    model = Sequential()
    model.add(vgg16)

    with open(filename, 'rb') as fp:
        layers = pickle.load(fp)
    for l in layers:
        cls = getattr(keras_layers, l['class'])
        if 'weights' in l:
            layer = cls(**l['kwargs'])
            model.add(layer)
            model.layers[-1].set_weights(l['weights'])
        else:
            model.add(cls())

    model.trainable = False
    return model

```

## 2 Exercise 1

```
[3]: # Load the training and test CIFAR10 data
(x_train, y_train), (x_test, y_test) = load_cifar10()
```

Downloading data from <https://www.cs.toronto.edu/~kriz/cifar-10-python.tar.gz>  
170500096/170498071 [=====] - 3s 0us/step

```
[ ]: # Normalize the train and test data
x_train_n = x_train / 255
x_test_n = x_test / 255

# Check if only 3 classes were loaded (no output should be printed)
for e in y_train:
    if e[0] not in [0,1,2]:
        print(e[0])
```

```
[ ]: from tensorflow.keras import utils

n_classes = 3

# Convert output data to one-hot encoding
y_train_n = utils.to_categorical(y_train, n_classes)
y_test_n = utils.to_categorical(y_test, n_classes)
```

```
[ ]: from tensorflow.keras import Sequential
from tensorflow.keras.layers import Dense
from tensorflow.keras import optimizers
from tensorflow.keras.layers import Conv2D, MaxPooling2D, AveragePooling2D, \
    Flatten, Dropout
from tensorflow.keras.callbacks import EarlyStopping, CSVLogger

# Build the CIFAR10 model architecture
model = Sequential()
model.add(Conv2D(8, (5, 5), activation='relu', input_shape=(32, 32, 3)))
model.add(MaxPooling2D(pool_size=(2, 2)))
model.add(Conv2D(16, (3, 3), strides=(2,2), activation='relu'))
model.add(AveragePooling2D(pool_size=(2, 2)))
model.add(Flatten())
model.add(Dense(8, activation='tanh'))
model.add(Dense(n_classes, activation='softmax'))

# Compile the model and print model architecture
model.compile(optimizer=optimizers.RMSprop(learning_rate=0.003),
              loss='categorical_crossentropy',
              metrics=['accuracy'])
model.summary()
```

```

# Implement early stopping monitoring validation accuracy
callback = EarlyStopping(monitor='val_accuracy',
                          patience=10,
                          restore_best_weights=True)

# Log training data in the indicated CSV file
log_task1 = CSVLogger('my_civar10.csv')

# Train the model
batch_size = 128
epochs = 500
model.fit(x_train_n,
          y_train_n,
          batch_size=batch_size,
          epochs=epochs,
          validation_split=0.2,
          callbacks=[callback, log_task1])

```

Model: "sequential\_7"

Layer (type)	Output Shape	Param #
conv2d (Conv2D)	(None, 28, 28, 8)	608
max_pooling2d (MaxPooling2D)	(None, 14, 14, 8)	0
conv2d_1 (Conv2D)	(None, 6, 6, 16)	1168
average_pooling2d (AveragePo	(None, 3, 3, 16)	0
flatten_7 (Flatten)	(None, 144)	0
dense_13 (Dense)	(None, 8)	1160
dense_14 (Dense)	(None, 3)	27

Total params: 2,963  
Trainable params: 2,963  
Non-trainable params: 0

```

Epoch 1/500
94/94 [=====] - 1s 6ms/step - loss: 0.9172 - accuracy:
0.5718 - val_loss: 0.9488 - val_accuracy: 0.5113
Epoch 2/500
94/94 [=====] - 0s 5ms/step - loss: 0.7498 - accuracy:
0.6758 - val_loss: 0.6664 - val_accuracy: 0.7343
Epoch 3/500
94/94 [=====] - 0s 5ms/step - loss: 0.6778 - accuracy:

```

0.7107 - val\_loss: 0.6071 - val\_accuracy: 0.7557  
Epoch 4/500  
94/94 [=====] - 0s 5ms/step - loss: 0.6342 - accuracy:  
0.7352 - val\_loss: 0.6572 - val\_accuracy: 0.7210  
Epoch 5/500  
94/94 [=====] - 0s 5ms/step - loss: 0.5902 - accuracy:  
0.7538 - val\_loss: 0.5681 - val\_accuracy: 0.7710  
Epoch 6/500  
94/94 [=====] - 0s 5ms/step - loss: 0.5556 - accuracy:  
0.7712 - val\_loss: 0.5319 - val\_accuracy: 0.7933  
Epoch 7/500  
94/94 [=====] - 0s 4ms/step - loss: 0.5265 - accuracy:  
0.7832 - val\_loss: 0.4979 - val\_accuracy: 0.8007  
Epoch 8/500  
94/94 [=====] - 0s 5ms/step - loss: 0.5014 - accuracy:  
0.7976 - val\_loss: 0.4851 - val\_accuracy: 0.8007  
Epoch 9/500  
94/94 [=====] - 0s 5ms/step - loss: 0.4874 - accuracy:  
0.8020 - val\_loss: 0.4577 - val\_accuracy: 0.8227  
Epoch 10/500  
94/94 [=====] - 0s 5ms/step - loss: 0.4745 - accuracy:  
0.8067 - val\_loss: 0.4667 - val\_accuracy: 0.8150  
Epoch 11/500  
94/94 [=====] - 0s 5ms/step - loss: 0.4576 - accuracy:  
0.8162 - val\_loss: 0.4599 - val\_accuracy: 0.8180  
Epoch 12/500  
94/94 [=====] - 0s 5ms/step - loss: 0.4456 - accuracy:  
0.8223 - val\_loss: 0.4813 - val\_accuracy: 0.8133  
Epoch 13/500  
94/94 [=====] - 0s 5ms/step - loss: 0.4402 - accuracy:  
0.8247 - val\_loss: 0.4650 - val\_accuracy: 0.8140  
Epoch 14/500  
94/94 [=====] - 0s 5ms/step - loss: 0.4313 - accuracy:  
0.8288 - val\_loss: 0.4428 - val\_accuracy: 0.8280  
Epoch 15/500  
94/94 [=====] - 0s 5ms/step - loss: 0.4172 - accuracy:  
0.8344 - val\_loss: 0.4678 - val\_accuracy: 0.8157  
Epoch 16/500  
94/94 [=====] - 0s 4ms/step - loss: 0.4134 - accuracy:  
0.8351 - val\_loss: 0.4249 - val\_accuracy: 0.8353  
Epoch 17/500  
94/94 [=====] - 1s 5ms/step - loss: 0.4058 - accuracy:  
0.8365 - val\_loss: 0.4124 - val\_accuracy: 0.8430  
Epoch 18/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3955 - accuracy:  
0.8430 - val\_loss: 0.4277 - val\_accuracy: 0.8313  
Epoch 19/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3878 - accuracy:



0.8466 - val\_loss: 0.4089 - val\_accuracy: 0.8367  
Epoch 20/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3865 - accuracy:  
0.8499 - val\_loss: 0.5154 - val\_accuracy: 0.7947  
Epoch 21/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3827 - accuracy:  
0.8513 - val\_loss: 0.4198 - val\_accuracy: 0.8393  
Epoch 22/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3752 - accuracy:  
0.8518 - val\_loss: 0.4005 - val\_accuracy: 0.8447  
Epoch 23/500  
94/94 [=====] - 0s 4ms/step - loss: 0.3663 - accuracy:  
0.8551 - val\_loss: 0.4908 - val\_accuracy: 0.8120  
Epoch 24/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3641 - accuracy:  
0.8571 - val\_loss: 0.4103 - val\_accuracy: 0.8430  
Epoch 25/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3591 - accuracy:  
0.8580 - val\_loss: 0.3885 - val\_accuracy: 0.8547  
Epoch 26/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3537 - accuracy:  
0.8607 - val\_loss: 0.4419 - val\_accuracy: 0.8363  
Epoch 27/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3477 - accuracy:  
0.8650 - val\_loss: 0.3892 - val\_accuracy: 0.8490  
Epoch 28/500  
94/94 [=====] - 0s 4ms/step - loss: 0.3448 - accuracy:  
0.8679 - val\_loss: 0.4389 - val\_accuracy: 0.8340  
Epoch 29/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3396 - accuracy:  
0.8660 - val\_loss: 0.3977 - val\_accuracy: 0.8500  
Epoch 30/500  
94/94 [=====] - 0s 4ms/step - loss: 0.3386 - accuracy:  
0.8673 - val\_loss: 0.4488 - val\_accuracy: 0.8283  
Epoch 31/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3359 - accuracy:  
0.8698 - val\_loss: 0.3940 - val\_accuracy: 0.8473  
Epoch 32/500  
94/94 [=====] - 0s 4ms/step - loss: 0.3290 - accuracy:  
0.8699 - val\_loss: 0.4283 - val\_accuracy: 0.8343  
Epoch 33/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3222 - accuracy:  
0.8747 - val\_loss: 0.3796 - val\_accuracy: 0.8540  
Epoch 34/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3185 - accuracy:  
0.8778 - val\_loss: 0.3872 - val\_accuracy: 0.8553  
Epoch 35/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3212 - accuracy:

0.8730 - val\_loss: 0.4123 - val\_accuracy: 0.8397  
Epoch 36/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3160 - accuracy:  
0.8738 - val\_loss: 0.3843 - val\_accuracy: 0.8533  
Epoch 37/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3122 - accuracy:  
0.8777 - val\_loss: 0.3735 - val\_accuracy: 0.8587  
Epoch 38/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3127 - accuracy:  
0.8755 - val\_loss: 0.3968 - val\_accuracy: 0.8450  
Epoch 39/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3069 - accuracy:  
0.8798 - val\_loss: 0.4014 - val\_accuracy: 0.8417  
Epoch 40/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3056 - accuracy:  
0.8823 - val\_loss: 0.4605 - val\_accuracy: 0.8237  
Epoch 41/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3014 - accuracy:  
0.8811 - val\_loss: 0.3749 - val\_accuracy: 0.8650  
Epoch 42/500  
94/94 [=====] - 0s 5ms/step - loss: 0.3015 - accuracy:  
0.8819 - val\_loss: 0.3943 - val\_accuracy: 0.8593  
Epoch 43/500  
94/94 [=====] - 0s 5ms/step - loss: 0.2996 - accuracy:  
0.8835 - val\_loss: 0.4209 - val\_accuracy: 0.8373  
Epoch 44/500  
94/94 [=====] - 0s 5ms/step - loss: 0.2928 - accuracy:  
0.8851 - val\_loss: 0.3775 - val\_accuracy: 0.8687  
Epoch 45/500  
94/94 [=====] - 0s 5ms/step - loss: 0.2901 - accuracy:  
0.8882 - val\_loss: 0.4303 - val\_accuracy: 0.8313  
Epoch 46/500  
94/94 [=====] - 0s 4ms/step - loss: 0.2915 - accuracy:  
0.8869 - val\_loss: 0.4693 - val\_accuracy: 0.8233  
Epoch 47/500  
94/94 [=====] - 0s 5ms/step - loss: 0.2878 - accuracy:  
0.8877 - val\_loss: 0.3719 - val\_accuracy: 0.8610  
Epoch 48/500  
94/94 [=====] - 0s 5ms/step - loss: 0.2852 - accuracy:  
0.8861 - val\_loss: 0.3751 - val\_accuracy: 0.8647  
Epoch 49/500  
94/94 [=====] - 0s 5ms/step - loss: 0.2818 - accuracy:  
0.8891 - val\_loss: 0.4302 - val\_accuracy: 0.8427  
Epoch 50/500  
94/94 [=====] - 0s 5ms/step - loss: 0.2842 - accuracy:  
0.8893 - val\_loss: 0.4167 - val\_accuracy: 0.8477  
Epoch 51/500  
94/94 [=====] - 0s 5ms/step - loss: 0.2788 - accuracy:

```

0.8915 - val_loss: 0.4626 - val_accuracy: 0.8300
Epoch 52/500
94/94 [=====] - 0s 5ms/step - loss: 0.2767 - accuracy:
0.8950 - val_loss: 0.4610 - val_accuracy: 0.8333
Epoch 53/500
94/94 [=====] - 0s 5ms/step - loss: 0.2742 - accuracy:
0.8938 - val_loss: 0.3817 - val_accuracy: 0.8633
Epoch 54/500
94/94 [=====] - 0s 5ms/step - loss: 0.2761 - accuracy:
0.8933 - val_loss: 0.4188 - val_accuracy: 0.8477

```

```
[ ]: <tensorflow.python.keras.callbacks.History at 0x7f9efe11e110>
```

## 2.0.1 Plot validation loss and accuracy curves

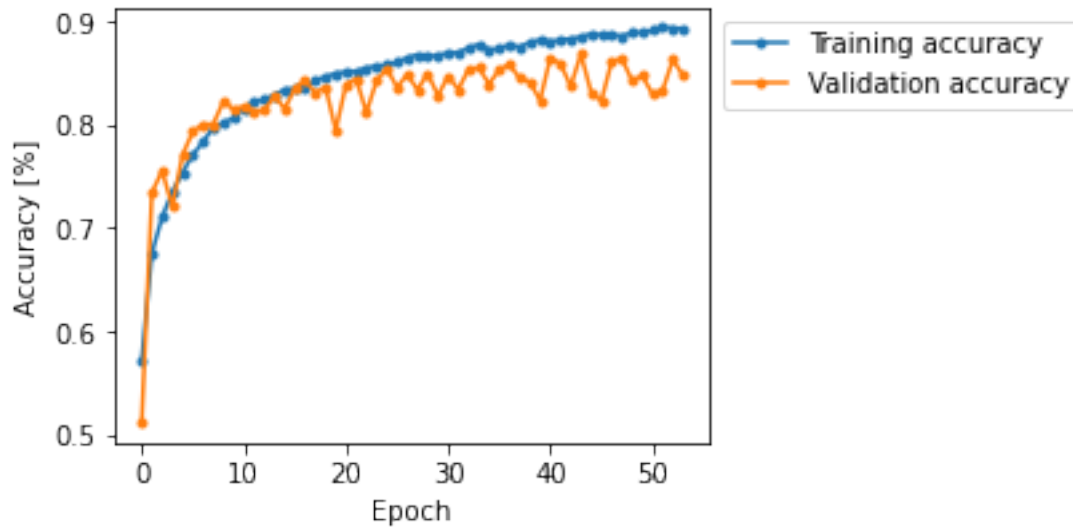
```
[ ]: import pandas as pd

# Load the CSV with saved training data
df = pd.read_csv('my_cifar10.csv')
print(df[df.epoch == 0])
```

epoch	accuracy	loss	val_accuracy	val_loss	
0	0	0.571833	0.917225	0.511333	0.948794

```
[ ]: import matplotlib as mpl
import matplotlib.pyplot as plt

# Plot training and validation accuracy w.r.t. epoch for CIFAR10 model
plt.figure(figsize=(4,3))
ax = plt.gca()
lines = []
FEATURES = ['accuracy', 'val_accuracy']
for feature in FEATURES:
    lines.append(ax.plot(df["epoch"], df[feature], marker='.')[0])
plt.xlabel("Epoch")
plt.ylabel("Accuracy [%]")
lgd = plt.legend(lines, ["Training accuracy", "Validation accuracy"],
                 loc="best", bbox_to_anchor=(1,1))
plt.show()
```



### 2.0.2 Statistical tests on CIFAR classifier

```
[ ]: # Compute loss and accuracy on the test set
print(np.shape(y_test_n))
test_loss, test_accuracy = model.evaluate(x_test_n, y_test_n)
print("Test accuracy is: %g" % test_accuracy)

(3000, 3)
94/94 [=====] - 0s 2ms/step - loss: 0.3649 - accuracy:
0.8640
Test accuracy is: 0.864
```

```
[2]: # Compute confidence interval for accuracy using binomial distribution
import numpy as np
import scipy.stats as st
from statsmodels.stats.proportion import proportion_confint

test_accuracy = 0.856333315372467
n = 3000

proportion_confint(test_accuracy * n, n, method='binom_test', alpha=0.05)
```

[2]: (0.8428686580662224, 0.8682027279962743)

### 2.0.3 Save the model

```
[ ]: # Save the model
save_keras_model(model, filename='/content/mn_task1.h5')
```

None

### 3 Exercise 2

```
[6]: # Load RPS data
(x_train, y_train), (x_test, y_test) = load_rps(download=True)
```

Downloading rps images in /content/rps (may take a couple of minutes)  
Loading training set...  
Loaded 1500 images for training  
Loading test set...  
Loaded 300 images for testing

```
[7]: import torch
import tensorflow as tf
from tensorflow.keras import applications
from keras.preprocessing.image import img_to_array, array_to_img

# Resize the input images and normalize them according to VGG16 normalization
# factors
def process_vgg16(x):
    x_n = [e.resize((224,224)) for e in x]
    for i in range(len(x)):
        bgr = img_to_array(x_n[i])[..., ::-1]
        mean = [103.939, 116.779, 123.68]
        bgr -= mean
        x_n[i] = bgr
    return x_n

# Process train and test set
x_train_n = tf.convert_to_tensor(process_vgg16(x_train))
x_test_n = tf.convert_to_tensor(process_vgg16(x_test))
```

```
[8]: from tensorflow.keras import utils

LABELS = set(y_train)
MAP = {'scissors': 0, 'paper': 1, 'rock': 2}
print(MAP)

# Convert string labels to numerical ones according to MAP
mapfunc = np.vectorize(lambda x: MAP[x])

# Convert numerical labels to one-hot encoding
y_train_n = utils.to_categorical(mapfunc(y_train), len(LABELS))
y_test_n = utils.to_categorical(mapfunc(y_test), len(LABELS))
```

```
{'scissors': 0, 'paper': 1, 'rock': 2}
```

```
[9]: # Download VGG16 convolution weights and architecture
```

```

from tensorflow.keras import Sequential, optimizers, applications
from tensorflow.keras.layers import Dense, Flatten, Dropout
from tensorflow.keras.layers import Conv2D, MaxPooling2D, AveragePooling2D
from tensorflow.keras.callbacks import EarlyStopping, CSVLogger

# Build the VGG16 network and download pre-trained weights and remove the last
# dense layers.
vgg16 = applications.VGG16(weights='imagenet',
                           include_top=False,
                           input_shape=(224, 224, 3))

# Freezes the network weights
vgg16.trainable = False

```

```

[ ]: # Build VGG16-based classifier
net = Sequential()
net.add(vgg16)
net.add(Flatten())
net.add(Dense(128, activation='relu'))
net.add(Dropout(0.25))
net.add(Dense(3, activation='softmax'))

# Compile and print network architecture
net.compile(optimizer=optimizers.Adam(learning_rate=0.001),
           loss='categorical_crossentropy',
           metrics=['acc'])
net.summary()

# Implement early stopping monitoring validation loss
es = EarlyStopping(monitor='val_loss', patience=10, restore_best_weights=True)

# Save training loss and accuracy over epochs in indicated CSV
log_task2_noaug = CSVLogger('my_vgg16_noaug.csv')

# Fit the model with not data augmented training and validation data
history = net.fit(x_train_n,
                 y_train_n,
                 batch_size=8,
                 epochs=50,
                 validation_split=0.2,
                 verbose=1,
                 callbacks=[es, log_task2_noaug])

```

```

[ ]: # Evaluate non-data-augmented model on test set
scores = net.evaluate(x_test_n, y_test_n)
print('Test loss: {} - Accuracy: {}'.format(*scores))

```

```
# Save the model
save_keras_model(net, '/content/yinn_task2_noaug.h5')
```

```
10/10 [=====] - 1s 118ms/step - loss: 0.5268 - acc:
0.7733
```

```
Test loss: 0.5268241763114929 - Accuracy: 0.7733333110809326
```

```
None
```

```
[10]: from tensorflow.keras.preprocessing.image import ImageDataGenerator

train_gen = ImageDataGenerator(width_shift_range=0.15,      # horizontal
                               ↳translation
                               height_shift_range=0.15,    # vertical translation
                               channel_shift_range=0.3,    # random channel
                               ↳shifts
                               rotation_range=360,         # rotation
                               zoom_range=0.3,            # zoom in/out randomly
                               shear_range=15,           # deformation
                               )
val_gen = ImageDataGenerator()

# Generate data-augmented training and validation set
train_loader = train_gen.flow(x_train_n, y_train_n, batch_size=40)
validation_loader = train_gen.flow(x_train_n, y_train_n, batch_size=10)
```

```
[12]: # Build VGG16-based classifier
net2 = Sequential()
net2.add(vgg16)
net2.add(Flatten())
net2.add(Dense(128, activation='relu'))
net2.add(Dropout(0.25))
net2.add(Dense(3, activation='softmax'))

# Implement early stopping monitoring validation loss
es2 = EarlyStopping(monitor='val_loss', patience=10, restore_best_weights=True)

# Compile and print network architecture
net2.compile(optimizer=optimizers.Adam(learning_rate=0.001),
             loss='categorical_crossentropy',
             metrics=['acc'])
net2.summary()

# Save training loss and accuracy over epochs in indicated CSV
log_aug = CSVLogger('my_vgg16_aug.csv')

# Fit the model with data augmented training and validation data
history = net2.fit(train_loader,
```

```
batch_size=16,  
epochs=50,  
validation_data=validation_loader,  
verbose=1,  
callbacks=[es2, log_aug])
```

Model: "sequential\_1"

Layer (type)	Output Shape	Param #
vgg16 (Functional)	(None, 7, 7, 512)	14714688
flatten_1 (Flatten)	(None, 25088)	0
dense_2 (Dense)	(None, 128)	3211392
dropout_1 (Dropout)	(None, 128)	0
dense_3 (Dense)	(None, 3)	387

Total params: 17,926,467  
Trainable params: 3,211,779  
Non-trainable params: 14,714,688

```
-----  
Epoch 1/50  
38/38 [=====] - 48s 1s/step - loss: 5.9368 - acc:  
0.4780 - val_loss: 0.9557 - val_acc: 0.4833  
Epoch 2/50  
38/38 [=====] - 32s 842ms/step - loss: 0.9711 - acc:  
0.5707 - val_loss: 0.9521 - val_acc: 0.5767  
Epoch 3/50  
38/38 [=====] - 32s 842ms/step - loss: 0.9213 - acc:  
0.6033 - val_loss: 0.7592 - val_acc: 0.6940  
Epoch 4/50  
38/38 [=====] - 32s 839ms/step - loss: 0.8037 - acc:  
0.6560 - val_loss: 0.6932 - val_acc: 0.7393  
Epoch 5/50  
38/38 [=====] - 32s 845ms/step - loss: 0.8075 - acc:  
0.6547 - val_loss: 0.6627 - val_acc: 0.7313  
Epoch 6/50  
38/38 [=====] - 33s 868ms/step - loss: 0.7375 - acc:  
0.6980 - val_loss: 0.6030 - val_acc: 0.7540  
Epoch 7/50  
38/38 [=====] - 33s 874ms/step - loss: 0.7086 - acc:  
0.7080 - val_loss: 0.5946 - val_acc: 0.7680  
Epoch 8/50  
38/38 [=====] - 32s 847ms/step - loss: 0.6479 - acc:  
0.7100 - val_loss: 0.5195 - val_acc: 0.8107
```



Epoch 9/50  
38/38 [=====] - 32s 844ms/step - loss: 0.6702 - acc:  
0.7167 - val\_loss: 0.5435 - val\_acc: 0.7847  
Epoch 10/50  
38/38 [=====] - 32s 849ms/step - loss: 0.6077 - acc:  
0.7500 - val\_loss: 0.4991 - val\_acc: 0.8180  
Epoch 11/50  
38/38 [=====] - 32s 843ms/step - loss: 0.6208 - acc:  
0.7333 - val\_loss: 0.4954 - val\_acc: 0.8060  
Epoch 12/50  
38/38 [=====] - 32s 851ms/step - loss: 0.6244 - acc:  
0.7313 - val\_loss: 0.5026 - val\_acc: 0.8060  
Epoch 13/50  
38/38 [=====] - 32s 848ms/step - loss: 0.5998 - acc:  
0.7640 - val\_loss: 0.4789 - val\_acc: 0.8127  
Epoch 14/50  
38/38 [=====] - 32s 839ms/step - loss: 0.5802 - acc:  
0.7507 - val\_loss: 0.4533 - val\_acc: 0.8273  
Epoch 15/50  
38/38 [=====] - 32s 846ms/step - loss: 0.5767 - acc:  
0.7533 - val\_loss: 0.4746 - val\_acc: 0.8233  
Epoch 16/50  
38/38 [=====] - 32s 839ms/step - loss: 0.5643 - acc:  
0.7600 - val\_loss: 0.4329 - val\_acc: 0.8253  
Epoch 17/50  
38/38 [=====] - 32s 852ms/step - loss: 0.5584 - acc:  
0.7673 - val\_loss: 0.4671 - val\_acc: 0.8067  
Epoch 18/50  
38/38 [=====] - 32s 850ms/step - loss: 0.5940 - acc:  
0.7587 - val\_loss: 0.4413 - val\_acc: 0.8300  
Epoch 19/50  
38/38 [=====] - 32s 844ms/step - loss: 0.5850 - acc:  
0.7573 - val\_loss: 0.4237 - val\_acc: 0.8373  
Epoch 20/50  
38/38 [=====] - 32s 841ms/step - loss: 0.5519 - acc:  
0.7820 - val\_loss: 0.4195 - val\_acc: 0.8373  
Epoch 21/50  
38/38 [=====] - 32s 845ms/step - loss: 0.5243 - acc:  
0.7867 - val\_loss: 0.4205 - val\_acc: 0.8433  
Epoch 22/50  
38/38 [=====] - 32s 840ms/step - loss: 0.5330 - acc:  
0.7800 - val\_loss: 0.4232 - val\_acc: 0.8427  
Epoch 23/50  
38/38 [=====] - 32s 848ms/step - loss: 0.5486 - acc:  
0.7927 - val\_loss: 0.4149 - val\_acc: 0.8393  
Epoch 24/50  
38/38 [=====] - 32s 843ms/step - loss: 0.5066 - acc:  
0.7987 - val\_loss: 0.4016 - val\_acc: 0.8480

Epoch 25/50  
38/38 [=====] - 32s 838ms/step - loss: 0.5062 - acc:  
0.8000 - val\_loss: 0.4163 - val\_acc: 0.8360  
Epoch 26/50  
38/38 [=====] - 31s 837ms/step - loss: 0.4952 - acc:  
0.7940 - val\_loss: 0.3879 - val\_acc: 0.8533  
Epoch 27/50  
38/38 [=====] - 31s 835ms/step - loss: 0.5135 - acc:  
0.7893 - val\_loss: 0.3924 - val\_acc: 0.8480  
Epoch 28/50  
38/38 [=====] - 31s 830ms/step - loss: 0.5359 - acc:  
0.7933 - val\_loss: 0.3887 - val\_acc: 0.8547  
Epoch 29/50  
38/38 [=====] - 32s 849ms/step - loss: 0.4884 - acc:  
0.8040 - val\_loss: 0.3913 - val\_acc: 0.8540  
Epoch 30/50  
38/38 [=====] - 32s 839ms/step - loss: 0.4803 - acc:  
0.8040 - val\_loss: 0.4148 - val\_acc: 0.8447  
Epoch 31/50  
38/38 [=====] - 31s 836ms/step - loss: 0.5072 - acc:  
0.8060 - val\_loss: 0.3828 - val\_acc: 0.8527  
Epoch 32/50  
38/38 [=====] - 31s 833ms/step - loss: 0.4988 - acc:  
0.7980 - val\_loss: 0.4236 - val\_acc: 0.8580  
Epoch 33/50  
38/38 [=====] - 32s 844ms/step - loss: 0.4721 - acc:  
0.8093 - val\_loss: 0.4001 - val\_acc: 0.8580  
Epoch 34/50  
38/38 [=====] - 31s 835ms/step - loss: 0.4841 - acc:  
0.8100 - val\_loss: 0.3656 - val\_acc: 0.8753  
Epoch 35/50  
38/38 [=====] - 31s 833ms/step - loss: 0.4884 - acc:  
0.8067 - val\_loss: 0.3772 - val\_acc: 0.8547  
Epoch 36/50  
38/38 [=====] - 31s 834ms/step - loss: 0.5038 - acc:  
0.8060 - val\_loss: 0.3824 - val\_acc: 0.8627  
Epoch 37/50  
38/38 [=====] - 32s 839ms/step - loss: 0.4988 - acc:  
0.8007 - val\_loss: 0.3792 - val\_acc: 0.8600  
Epoch 38/50  
38/38 [=====] - 31s 840ms/step - loss: 0.4807 - acc:  
0.8133 - val\_loss: 0.3693 - val\_acc: 0.8727  
Epoch 39/50  
38/38 [=====] - 31s 836ms/step - loss: 0.4792 - acc:  
0.8053 - val\_loss: 0.3456 - val\_acc: 0.8720  
Epoch 40/50  
38/38 [=====] - 32s 837ms/step - loss: 0.4598 - acc:  
0.8120 - val\_loss: 0.4263 - val\_acc: 0.8493

```

Epoch 41/50
38/38 [=====] - 31s 835ms/step - loss: 0.4712 - acc:
0.8120 - val_loss: 0.3842 - val_acc: 0.8687
Epoch 42/50
38/38 [=====] - 31s 834ms/step - loss: 0.4660 - acc:
0.8060 - val_loss: 0.3825 - val_acc: 0.8673
Epoch 43/50
38/38 [=====] - 31s 836ms/step - loss: 0.4617 - acc:
0.8193 - val_loss: 0.3563 - val_acc: 0.8667
Epoch 44/50
38/38 [=====] - 32s 841ms/step - loss: 0.4561 - acc:
0.8227 - val_loss: 0.3650 - val_acc: 0.8647
Epoch 45/50
38/38 [=====] - 31s 835ms/step - loss: 0.4573 - acc:
0.8240 - val_loss: 0.3844 - val_acc: 0.8507
Epoch 46/50
38/38 [=====] - 32s 843ms/step - loss: 0.4898 - acc:
0.8020 - val_loss: 0.3444 - val_acc: 0.8740
Epoch 47/50
38/38 [=====] - 31s 836ms/step - loss: 0.4352 - acc:
0.8273 - val_loss: 0.3574 - val_acc: 0.8640
Epoch 48/50
38/38 [=====] - 32s 837ms/step - loss: 0.4651 - acc:
0.8187 - val_loss: 0.3359 - val_acc: 0.8793
Epoch 49/50
38/38 [=====] - 32s 841ms/step - loss: 0.4681 - acc:
0.8173 - val_loss: 0.3494 - val_acc: 0.8687
Epoch 50/50
38/38 [=====] - 31s 835ms/step - loss: 0.4628 - acc:
0.8113 - val_loss: 0.3382 - val_acc: 0.8760

```

```

[13]: # Evaluate non-data-augmented model on test set
scores = net2.evaluate(x_test_n, y_test_n)
print('Test loss: {} - Accuracy: {}'.format(*scores))

# Save the model
print(save_keras_model(net2, filename='/content/nn_task2_aug.h5'))

```

```

10/10 [=====] - 11s 439ms/step - loss: 0.2486 - acc:
0.9000
Test loss: 0.2485782653093338 - Accuracy: 0.8999999761581421
None

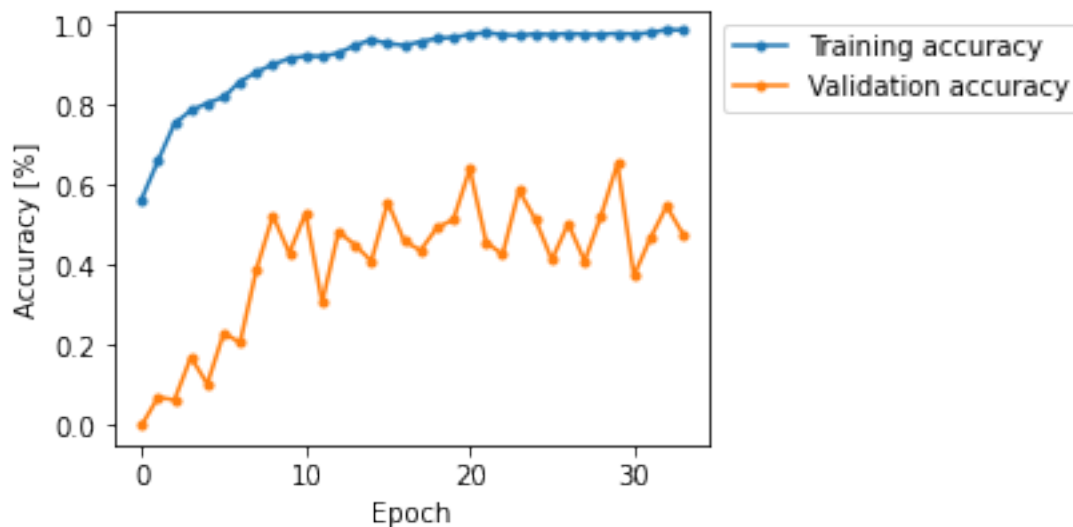
```

### 3.0.1 Plot validation loss and accuracy curves (non-data-augmented model)

```
[4]: import pandas as pd
import matplotlib as mpl
import matplotlib.pyplot as plt

df = pd.read_csv('my_vgg16_noaug.csv')
print(df[df.epoch == 0])
plt.figure(figsize=(4,3))
ax = plt.gca()
lines = []
FEATURES = ['acc', 'val_acc']
for feature in FEATURES:
    lines.append(ax.plot(df["epoch"],df[feature], marker='.')[0])
plt.xlabel("Epoch")
plt.ylabel("Accuracy [%]")
lgd = plt.legend(lines, ["Training accuracy", "Validation accuracy"],
                 loc="best", bbox_to_anchor=(1,1))
plt.show()
```

epoch	acc	loss	val_acc	val_loss	
0	0	0.565	0.955588	0.0	1.627829



### 3.0.2 Plot validation loss and accuracy curves (data augmented model)

```
[15]: import pandas as pd
import matplotlib as mpl
import matplotlib.pyplot as plt
```

```

df = pd.read_csv('my_vgg16_aug.csv')
print(df[df.epoch == 0])
plt.figure(figsize=(4,3))
ax = plt.gca()
lines = []
FEATURES = ['acc', 'val_acc']
for feature in FEATURES:
    lines.append(ax.plot(df["epoch"],df[feature], marker='.')[0])
plt.xlabel("Epoch")
plt.ylabel("Accuracy [%]")
lgd = plt.legend(lines, ["Training accuracy", "Validation accuracy"],
                 loc="best", bbox_to_anchor=(1,1))
plt.show()

```

	epoch	acc	loss	val_acc	val_loss
0	0	0.478	5.93678	0.483333	0.955677

